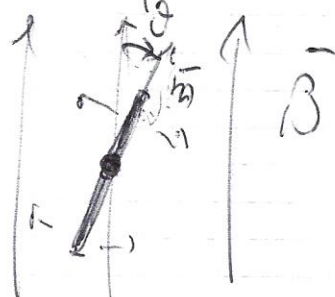


ES. #24 Forze magnetiche su dipoli - potenziale vettore

12/11/2021

1

(15-3)



$$\vec{U} = -\vec{m} \cdot \vec{B}$$

$$\vec{F} = -\nabla U = \nabla(\vec{m} \cdot \vec{B})$$

$$\vec{M} = \vec{m} \times \vec{B}$$

$$M = mB \sin \theta$$

I momenti di inerzia

$$M = I \frac{d\omega}{dt} = I \frac{d^2\theta}{dt^2}$$

$$\omega = \dot{\theta}$$

$$I \frac{d^2\theta}{dt^2} = -mB \sin \theta = -mB \theta$$

$$\frac{d^2\theta}{dt^2} = -\omega^2 \theta$$

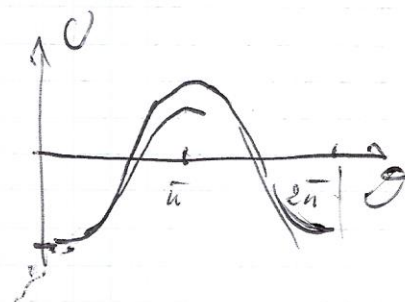
hyp.: piccole oscillazioni $\sin(\theta) \approx \theta$

$$\omega = \sqrt{mB/I}$$

$$\theta(t) = \theta_{\max} \sin(\omega t + \varphi)$$

$$U = -\vec{m} \cdot \vec{B} = -mB \cos \theta$$

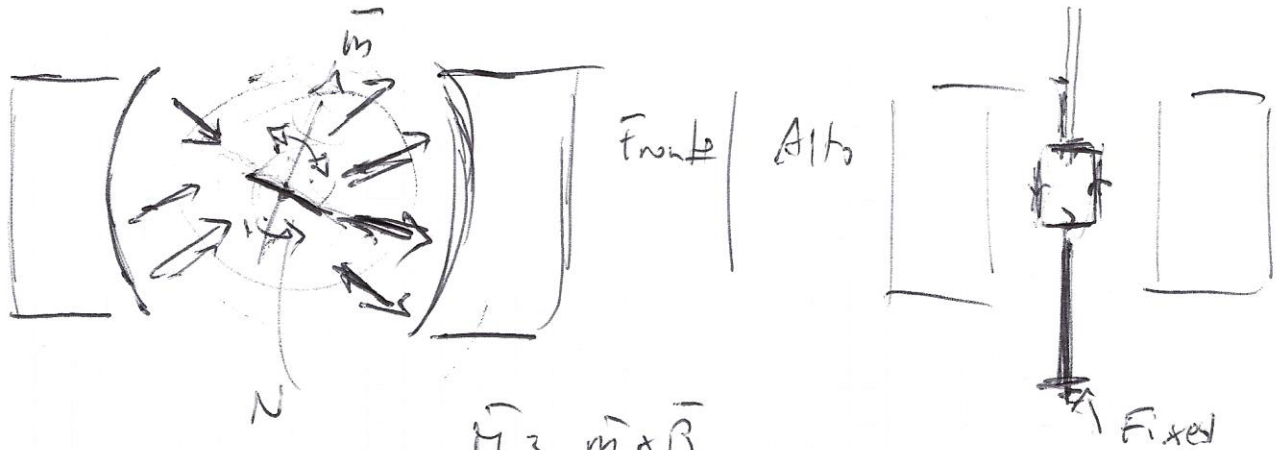
$$M = -\frac{dU}{d\theta}$$



(15-15)

Galvanometro di D'Arsonval

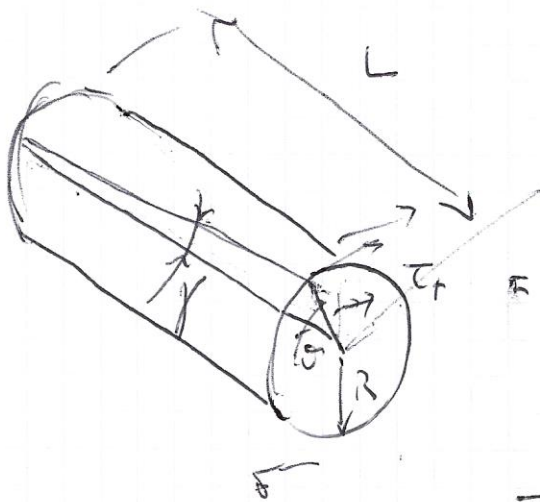
2



$$\vec{M} = \vec{m} \times \vec{B}$$

$$m = N I S = N I d^2$$

$$M_m = m B = N I d^2 B$$



$$\tau = G \gamma$$

$$\gamma L = \theta R$$

$$\tau_{\max} \equiv \tau(r=R) = G \theta R / L$$

$$M_t = \int \tau_r r dA = \frac{\tau_{\max}}{R} \int r^2 dA = \frac{\tau_{\max}}{R} \frac{\pi R^4}{2}$$

A = area della sezione circolare

J_z second moment of inertia

$$dA = r dr d\theta$$

$$M_t = \frac{\tau_{\max}}{R} J_z = \frac{\pi}{2} \frac{G R^4 \theta}{L} \quad \text{equ.} \quad M_t = N I d^2 B$$

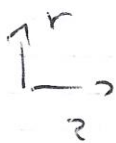
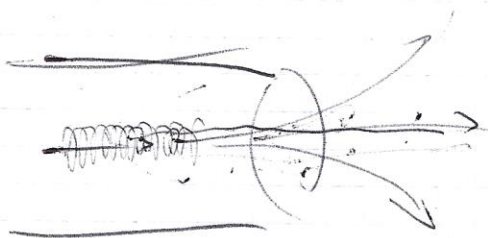
$d = 15 \text{ mm}; N = 25; B = 0.2 \text{ T}; L = 150 \text{ mm}; R = 50 \mu\text{m}; G = 5 \cdot 10^8 \text{ N/m}^2$
 $I = 0.1 \mu\text{A} \rightarrow \theta = 2.75 \text{ mrad } (= 0.16^\circ)$

(15-11)

Magnetic mirror

→ magnetic bottle

3



$$\frac{\partial B_z}{\partial z}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

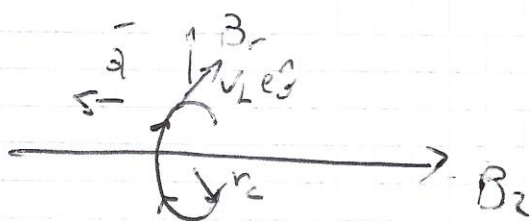
$$\frac{1}{r} \frac{\partial}{\partial r} (r B_r) + \frac{\partial B_z}{\partial z} = 0$$

$$\frac{\partial}{\partial r} (r B_r) = -r \frac{\partial B_z}{\partial z}$$

$$r B_r = -\frac{1}{2} r^2 \frac{\partial B_z}{\partial z}$$

$$B_r = -\frac{1}{2} r \frac{\partial B_z}{\partial z}$$

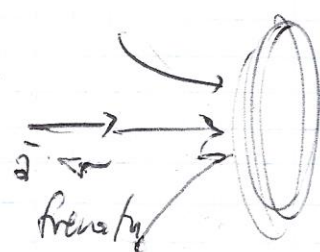
$$e^- \quad \vec{a} = -\frac{e}{m} v_L \hat{e}_\theta \times \vec{B}_r = -\frac{e}{m} v_L \hat{e}_\theta \times \left(-\frac{1}{2} r \frac{\partial B_z}{\partial z} \hat{e}_r \right)$$



$$= \frac{e v_L r_c}{2m} \frac{\partial B_z}{\partial z} \hat{e}_z = \frac{B_0}{B_z} =$$

$$= -\frac{v_L \omega_c r_c}{2} \frac{1}{B_0} \frac{\partial B_z}{\partial z} \hat{e}_z \Rightarrow$$

$$r_c = v_L / \omega_c$$



$$\vec{a} = -\frac{v_L^2}{2} \frac{1}{B_0} \frac{\partial B_z}{\partial z} \hat{e}_z = -\frac{v_L^2}{2 c^2} \hat{e}_z$$

$\frac{1}{c^2}$



$-e$

$$T = \frac{2\pi r_c}{v_L}$$

(4)

$$I = -e v_L / 2\pi r_c \rightarrow \mu$$

$$\mu = I S = I \pi r_c^2 = -\frac{e v_L}{2} r_c^2 = -\frac{m v_L^2}{2B}$$

$$\mu = +\frac{m v_L^2}{2B}$$

$$r_c = \frac{m v_L}{eB} \left(= \frac{v_L}{\omega_c} \right)$$

$$\vec{F}_2 = \text{grad } \mu = -\frac{m v_L^2}{2} \frac{1}{B_0} \frac{\partial B_2}{\partial z} = -\mu \frac{\partial B_2}{\partial z}$$

$$\vec{F} = \vec{\nabla} (\vec{\mu} \cdot \vec{B}) = \vec{\nabla} (\mu B_2) \approx \mu \vec{\nabla} B_2 \approx -\mu \frac{\partial B_2}{\partial z} \hat{z}$$

μ adiabatic invariant if $\mu = \text{const.}$

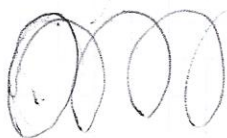
\hookrightarrow almost a constant of motion

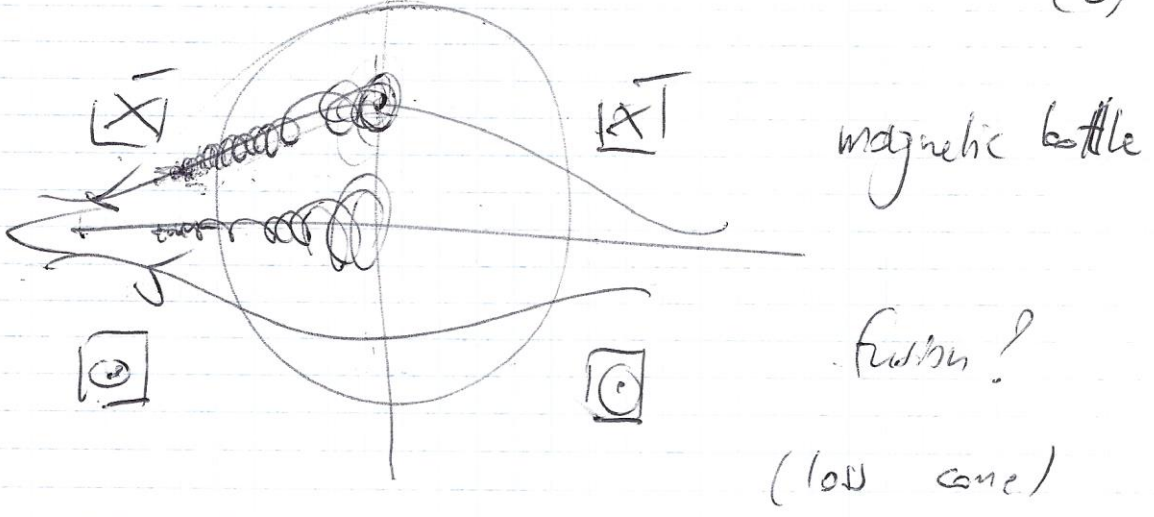
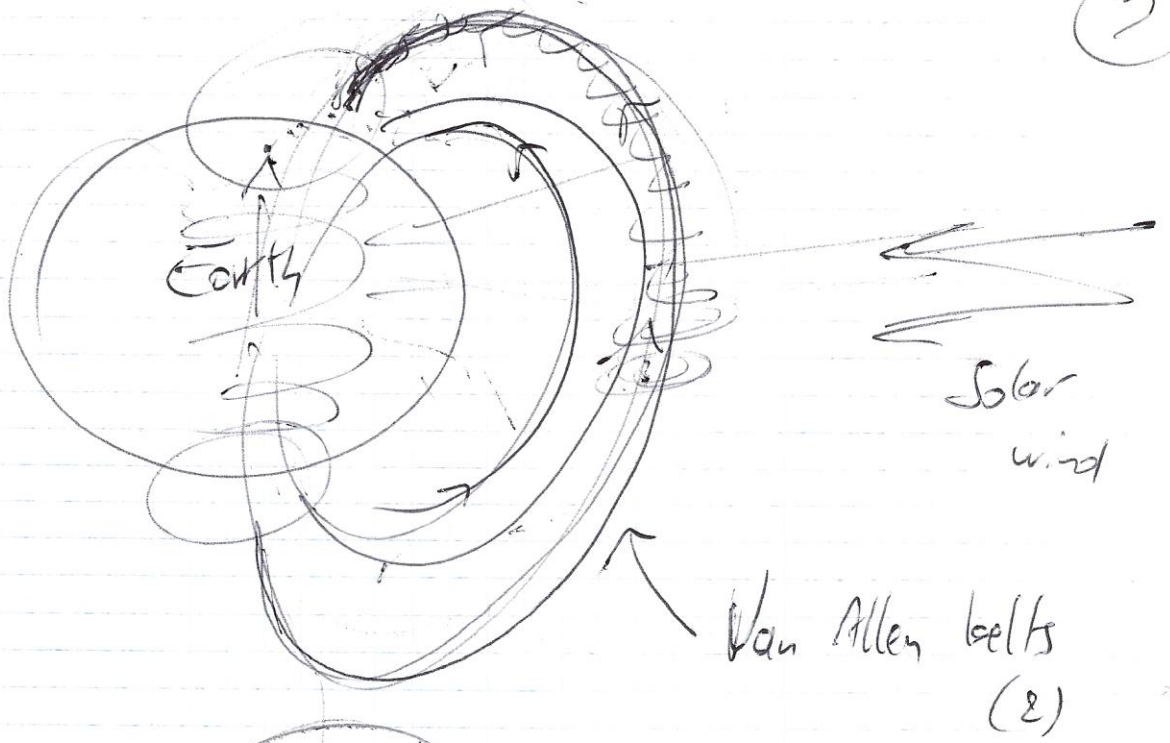
for periodic motion

$$\mathcal{J} = \oint \vec{p} \cdot d\vec{q} = \oint \vec{p} \cdot d\vec{l} =$$

$$(p = p_L = m v_L) = \int m v_L^2 \frac{dl}{v_L} = \frac{2}{2\pi} \oint m v_L^2 \frac{m}{qB} d\theta =$$

$$= 2 \frac{m}{q} \oint \mu d\theta \propto \mu T \quad (v_L = r_c \omega_c)$$





(S-13)

$\vec{A}_0(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{j}(\vec{r}')}{|\vec{r}-\vec{r}'|} d\tau'$

anche $= \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}'}{|\vec{r}-\vec{r}'|}$

$\vec{B}_0 = \nabla \times \vec{A}_0$

$\int_S \vec{B} \cdot d\vec{S} = \int_S (\nabla \times \vec{A}_0) \cdot d\vec{S} = \oint_{\partial S} \vec{A}_0 \cdot d\vec{l}$

$$\vec{A}_0(\vec{r}) = A_{0z}(r) \hat{e}_z$$

$$\begin{aligned}
 &= \vec{A}_{0z}(r) \hat{e}_z \\
 \int_r^{r+dr} B_z(r) l dr &= l \underbrace{\frac{\mu_0 I}{e \pi r}}_{B_z(r)} dr = A_{0z}(r) l - \underbrace{A_{0z}(r+dr) l}_{(A_{0z}(r) + dA_{0z}) l} = \\
 &= -l dA_{0z}
 \end{aligned}$$

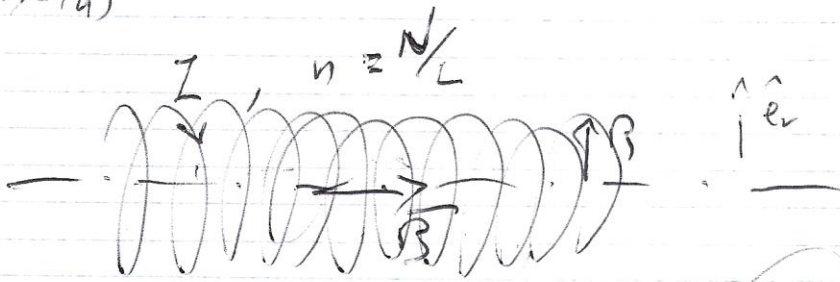
$$dA_{0z} = - \frac{\mu_0 I}{e \pi r} dr$$

~~$$A_{0z}(r) - A_{0z}(r_0) = \int_{r_0}^r dA_{0z} = - \frac{\mu_0 I}{e \pi} \log\left(\frac{r}{r_0}\right)$$~~

$$A_{0z}(r) - A_{0z}(r_0) = \int_{r_0}^r dA_{0z} = - \frac{\mu_0 I}{e \pi} \log\left(\frac{r}{r_0}\right)$$

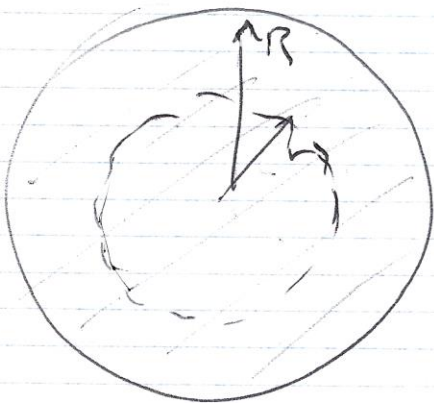
(15-14)

7



$A_{\phi}(r)$

$$\int_S \vec{B} \cdot d\vec{S} = \oint \vec{A} \cdot d\vec{l}$$



$r < R$

$$B_{0z} \pi r^2 = A_{\phi}(r) 2\pi r$$

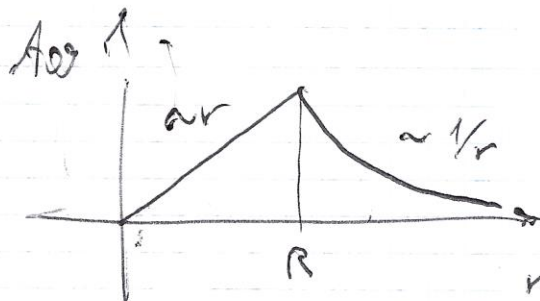
$$A_{\phi}(r) = \frac{1}{2} B_{0z} r = \frac{1}{2} \mu_0 n I r$$



$r > R$

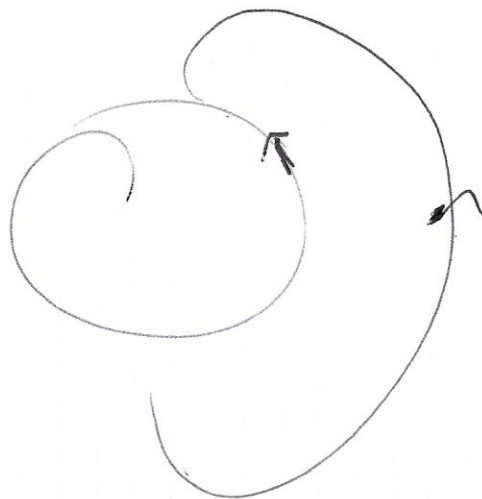
$$B_{0z} \pi R^2 = A_{\phi}(r) 2\pi r$$

$$A_{\phi}(r) = \frac{1}{2} B_{0z} \frac{R^2}{r} = \frac{1}{2} \mu_0 n I R^2 \frac{1}{r}$$



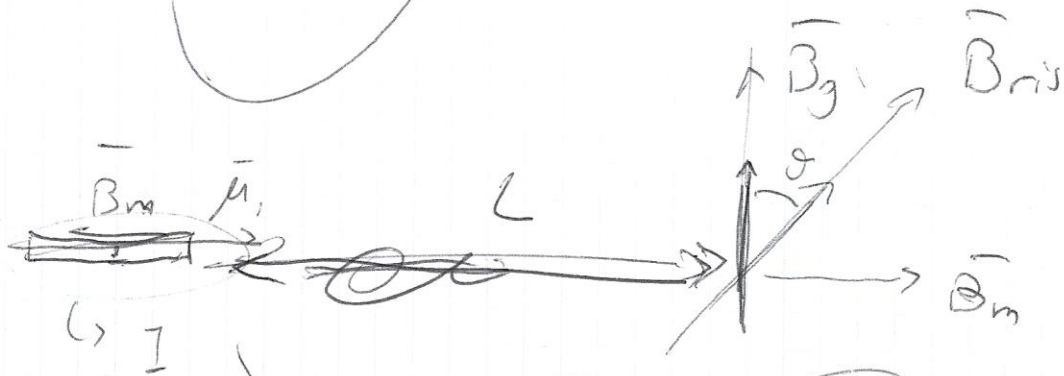
$$\vec{\nabla} \times \left(\frac{1}{r} \vec{e}_z \right) = \vec{0}$$

(25-12)



$B_g = \text{comp. orizz. del } \vec{B} \text{ terrestre}$ (8)

Magnete a sbarra
+
Ago magnetico



$$\omega = \sqrt{\frac{\mu B_g}{I}} \rightarrow \mu = \omega^2 I / B_g$$

$$B_g = B_{ris} \cos \theta = \frac{B_m}{\sin \theta} \cos \theta = B_m / \tan \theta$$

$$B_m = \frac{\mu_0}{2\pi} \frac{I}{L^3}$$

$$B_g = \frac{I}{\tan \theta} \frac{\mu_0}{2\pi} \frac{I}{L^3} = \frac{I}{\tan \theta} \frac{\mu_0}{2\pi L^3} \frac{\omega^2 I}{B_g} \frac{m}{\sqrt{m^2 + z^2}^{3/2}}$$

$$B_g = \left(\frac{\mu_0 \omega^2 I}{2\pi L^3 \tan \theta} \right)^{1/2}$$

$$I = 3.17 \cdot 10^{-2} \text{ kg m}^3$$

$$\omega = 2\pi \nu \Rightarrow \nu = 0.1 \text{ Hz}$$

$$L = 1 \text{ m} \Rightarrow \theta = 45^\circ$$

$$B_g = 5 \cdot 10^{-9} \text{ T} = 0.5 \text{ Gauss}$$