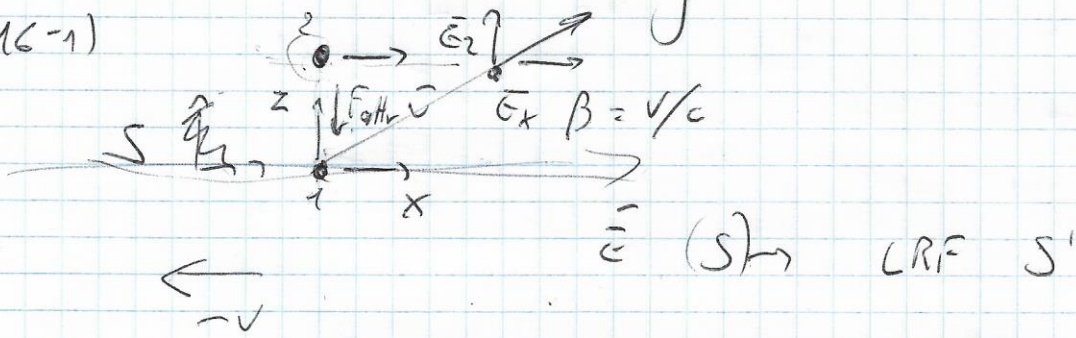


ES. #22 - Moto relativistico di cariche;
 induzione elettromagnetica

13/11/2021

(1)

(16-1)

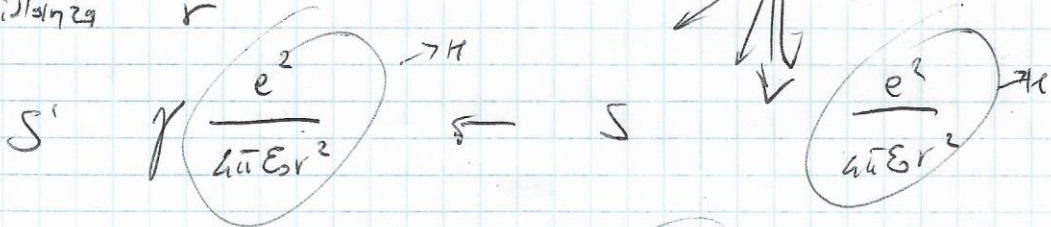


$$\vec{E}'_x = \frac{Q}{4\pi\epsilon_0} \frac{x}{(x^2+z'^2)^{3/2}} = \frac{Q}{4\pi\epsilon_0} \frac{\gamma x'}{(\gamma^2 x'^2 + z'^2)^{3/2}}$$

$$\vec{E}_z = \gamma \vec{E}'_z = \gamma \frac{Q}{4\pi\epsilon_0} \frac{z'}{(x'^2+z'^2)^{3/2}} = \frac{Q}{4\pi\epsilon_0} \frac{\gamma z'}{(\gamma^2 x'^2 + z'^2)^{3/2}}$$

$\vec{E}_x = \vec{E}'_x$
 $\vec{E}_z = \vec{E}'_z$

distanza r

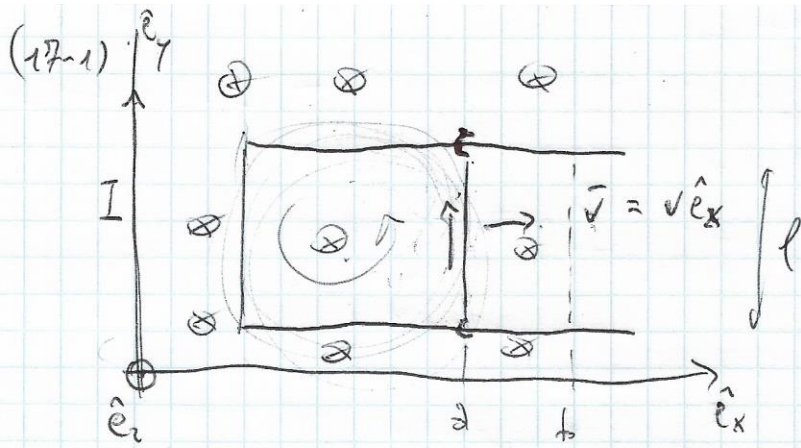


$\vec{F}'_{\perp} = \frac{1}{\gamma} \vec{F}_{\perp} = \frac{1}{\gamma} K$ forza totale

$\frac{1}{\gamma} K = \gamma K - F_{\text{attr}}$ $\gamma = 1/\sqrt{1-\beta^2}$

$F_{\text{attr}} = (\gamma - \frac{1}{\gamma}) K = \beta^2 \gamma K$ origine magnetica

$F_{\text{attr}} = \gamma \beta^2 \frac{e^2}{4\pi\epsilon_0 r^2} = e v B \left(\frac{\beta}{c} \frac{\gamma e}{4\pi\epsilon_0 r^2} \right)$ (Purcell)



$$f_i = - \frac{d\phi(\vec{B})}{dt} \quad (2)$$

$$\vec{E}_i = \vec{v} \times \vec{B}$$

Metodo (A) : $\vec{E}_i = \vec{v} \times \vec{B}_0 = -\frac{\mu_0 I v}{2\pi x} \hat{e}_x \times \hat{e}_z = \frac{\mu_0 I v}{2\pi x} \hat{e}_y$

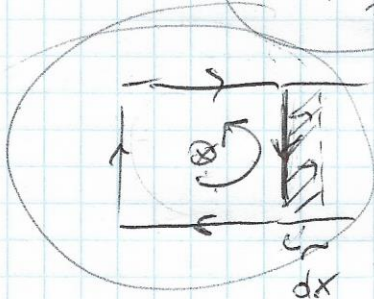
$$\vec{B}_0(x) = -\frac{\mu_0 I}{2\pi x} \hat{e}_z$$

$$f_i = \int \vec{E}_i \cdot d\vec{l} = \int_0^l (\vec{v} \times \vec{B}_0) \cdot dy \hat{e}_y = \frac{\mu_0 I v l}{2\pi x}$$

Metodo (B) : Faraday-Neumann

$$f_i = - \frac{d\phi(\vec{B})}{dt}$$

$$\phi = \int \vec{B} \cdot d\vec{S}$$



$$d\phi(B) = B_0(x) l dx$$

$$\frac{d\phi}{dt} = B_0(x) l \frac{dx}{dt} = B_0(x) l v$$

$$f_i = - \frac{d\phi}{dt} = -B_0(x) l v = -\frac{\mu_0 I l v}{2\pi x}$$

$$i = \frac{f_i}{R} = \frac{\mu_0 I l v}{2\pi R x}$$

Sulla corrente mobile $d\vec{F} = i_{ind} d\vec{l} \times \vec{B} \leadsto \vec{F} = i_{ind} \vec{l} \times \vec{B} =$

$$= i l B_0(x) \hat{e}_y \times (-\hat{e}_z) = -i l B_0 \hat{e}_x = -\frac{\mu_0 I l^2 v}{2\pi R x} \hat{e}_x = -\left(\frac{\mu_0 I l}{2\pi R}\right)^2 \frac{v}{R} \hat{e}_x$$

$$\overline{F}_{ext} = -\overline{F}$$

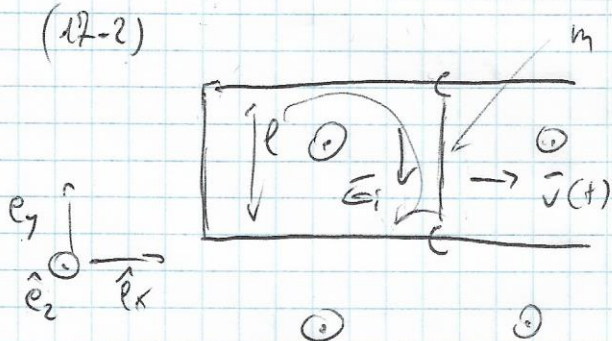
(9)

$$d\mathcal{L} = \overline{F}_{ext} \cdot d\vec{r} = F_{ext} dx$$

$$\mathcal{L} = \int_a^b \overline{F}_{ext} dx = \left(\frac{\mu_0 I l}{2\pi} \right)^2 \frac{v}{R} \int_a^b \frac{dx}{x^2} = \left(\frac{\mu_0 I l}{2\pi} \right)^2 \frac{v}{R} \frac{b-a}{ab}$$

$\hookrightarrow \left[-\frac{1}{x} \right]_a^b$

(17-2)



$$\overline{B}_0 = B_0 \hat{z}$$

$$\text{impulse } \vec{j} = m \vec{v}_0$$

$$\overline{E}_i = \vec{v} \times \overline{B}_0 = v B_0 \hat{x} \times \hat{z} = -v B_0 \hat{y}$$

$$f_i = \int \overline{E}_i \cdot d\vec{l} = -v B_0 l \quad \Rightarrow \quad \tau_{ind} = f_i / R = -v_0 B l / R$$

$\hookrightarrow \parallel \hat{e}_y$

$$\overline{F} = i l \hat{e}_y \times \overline{B}_0 = -\frac{v B_0^2 l^2}{R} \hat{x}$$

$v(t)$

$$\overline{F}_x = m \frac{dv}{dt} (v_x)$$

$$-\frac{B_0^2 l^2}{R} v = m \frac{dv}{dt} \quad \Rightarrow$$

$$\int_{v_0}^v \frac{dv'}{v'} = \left(-\frac{B_0^2 l^2}{mR} \right) \int_0^t dt'$$

$$v(t) = v_0 e^{-t/\tau}$$

$$\tau = mR / B_0^2 l^2$$

$$v = dx/dt \quad \int_{x_0}^x dx' = \int_0^t v dt' = v_0 \int_0^t e^{-t'/\tau} dt' = -v_0 \tau \left(e^{-t/\tau} - 1 \right)$$

$$x - x_0 = v_0 \tau (1 - e^{-t/\tau})$$

$$x = x_0 + v_0 \tau (1 - e^{-t/\tau})$$

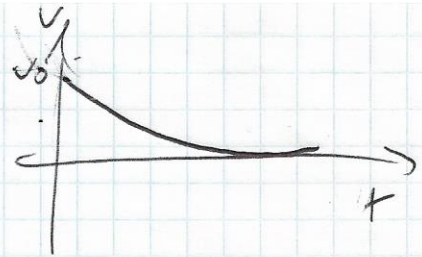
$$x_{\infty} = x_0 + v_0 \tau = x_0 + \frac{m R v_0}{B_0^2 l^2}$$

$$\bar{G} = \int_{\phi}^{+\infty} P_j dt = \int_{\phi}^{+\infty} R i^2 dt =$$

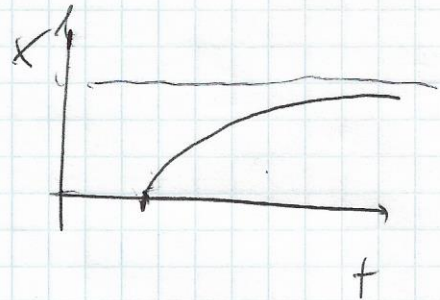
$$i(t) = -v(t) B_0 l / R = -\frac{B_0 l v_0}{R} e^{-t/\tau}$$

$$\frac{B_0^2 l^2 v_0}{R} \int_{\phi}^{+\infty} e^{-2t/\tau} dt = \frac{B_0^2 l^2 v_0}{R} \frac{\tau}{2} (e^{-2t/\tau}) \Big|_{\phi}^{+\infty} = \frac{1}{2} m v_0^2 = \text{Kinetic Energy}$$

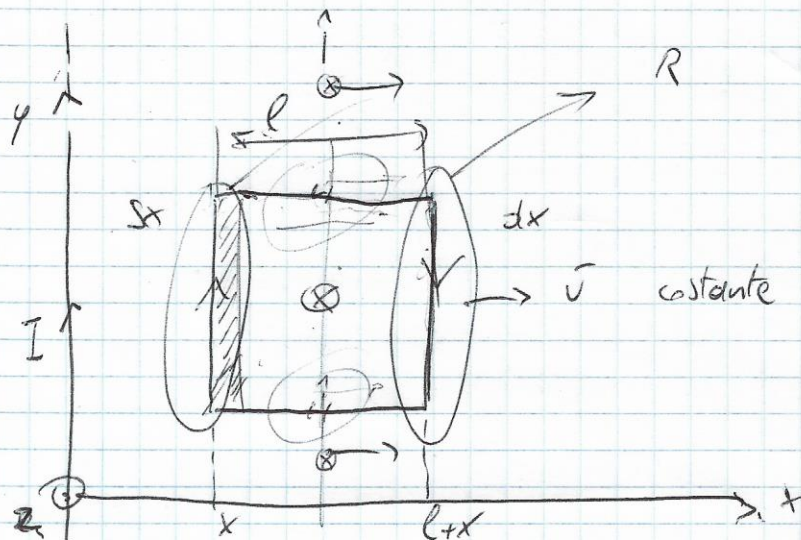
$$\frac{m R}{2 B_0^2 l^2}$$



(4)



(17-3)



$$f_i \Rightarrow i_{ind} = \frac{f_i}{R} \quad (5)$$

Metodo A: campo del motore

$$\vec{E}_i = \vec{v} \times \vec{B}_s$$

$$f_i = f_{i, dx} + f_{i, dx} = \underbrace{[\vec{v} \times \vec{B}_s(x)] \cdot l \hat{e}_y}_{\vec{E}_{i, dx}} + \underbrace{[\vec{v} \times \vec{B}_s(l+x)] \cdot l (-\hat{e}_y)}_{\vec{E}_{i, dx}} =$$

$$f_i = \oint \vec{E}_i \cdot d\vec{l}$$

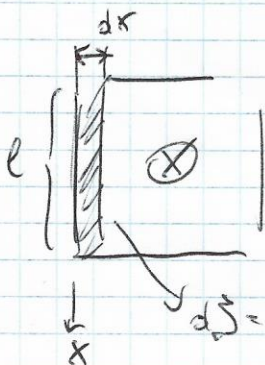
$$f_i = vl \frac{\mu_0 I}{2\pi x} - vl \frac{\mu_0 I}{2\pi(l+x)} = \frac{\mu_0 I l^2 v}{2\pi x(l+x)}$$

$$i_{ind} = f_i / R$$



Metodo B:

$$f_i = - \frac{d\phi}{dt} = - \frac{d}{dt} \int_x^{l+x} B_s(x') l dx' = - \frac{\mu_0 I l}{2\pi} \frac{d}{dt} \left[\log \left(\frac{l+x}{x} \right) \right]$$

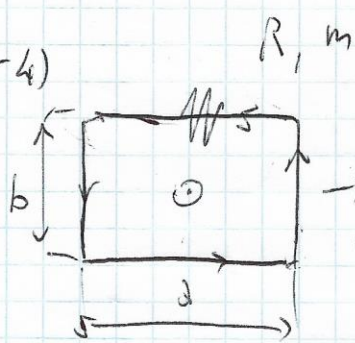


$$\frac{d}{dt} = \frac{d}{dx} \frac{dx}{dt} = v \frac{d}{dx}$$

$$f_i = \frac{\mu_0 I l v}{2\pi} \frac{d}{dx} \left[\log \left(\frac{x+l}{x} \right) \right] = \frac{\mu_0 I l^2 v}{2\pi x(x+l)}$$

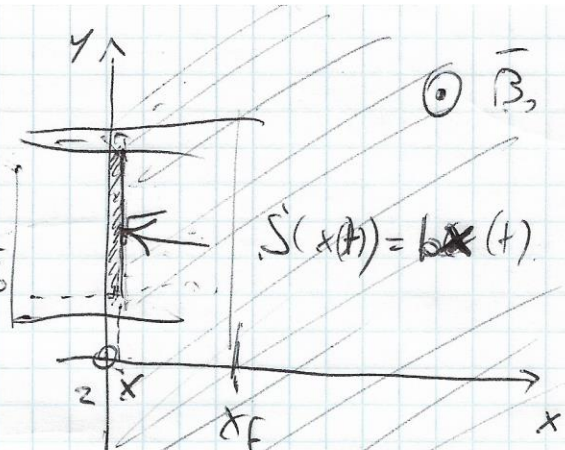
$$P_j = R I^2 = f_i / R$$

(17-4)



R, m

v_0



$$S(x(t)) = b \cdot x(t)$$

$v(t)$

$$\vec{E}_i = \vec{J} \times \vec{B}$$

6

$$f_i = - \frac{d\Phi}{dt} = - \frac{d}{dt} (B_0 S(x(t))) = - B_0 b \frac{dx(t)}{dt} = - B_0 b v(t)$$

$$i_{ind} = f_i / R = - B_0 b v / R$$

$$\vec{F} = i_{ind} b (-\hat{e}_y) \times B_0 \hat{e}_z = - i_{ind} b B_0 \hat{e}_x = - B_0^2 \frac{b^2}{R} v(t) \hat{e}_x$$

\hat{e}_x

$$\vec{F} = m \vec{a} \rightarrow \text{longo } \hat{e}_x$$

$$F_x = m \frac{dv}{dt}$$

↓

$$- \frac{B_0^2 b^2}{R} v(t) = m \frac{dv(t)}{dt}$$

$$dx = v dt$$

$$dv = - \frac{B_0^2 b^2}{mR} dx$$

$$\int_{v_0}^{v_f} dv' = - \frac{B_0^2 b^2}{mR} \int_{\phi}^x dx'$$

$$v = v_0 - \frac{B_0^2 b^2}{mR} x$$

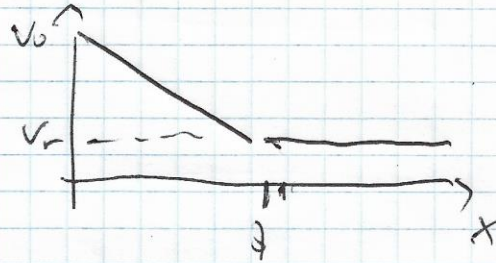
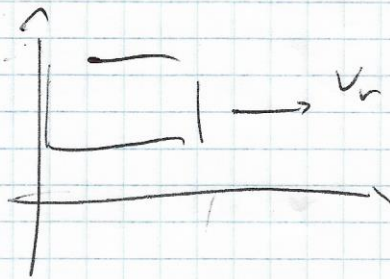
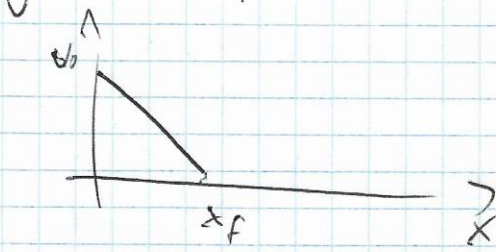
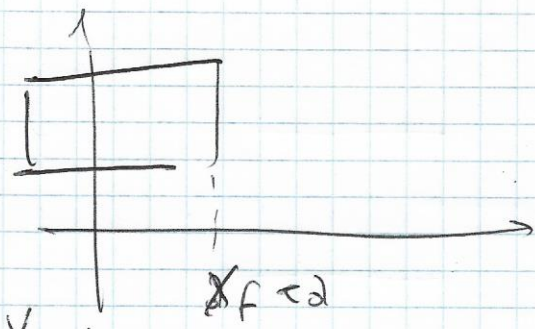
$x_{finale} = ?$

$$v_{finale} = 0$$

$$\rightarrow x_f = \frac{mR v_0}{B_0^2 b^2} \text{ se } x_f < d$$

$$\frac{mR v_0}{B_0^2 b^2} < d$$

$$v = v_0 - \frac{B_0^2 b^2}{mR} d \geq 0$$



7