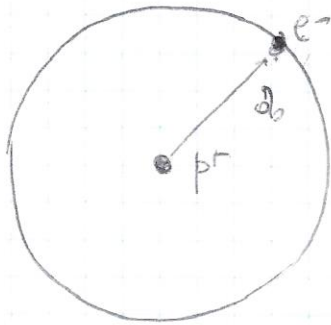


ES #6 Energia elettrostatica; operatori differenziali

Def 8/1/20

(3-6)



$$* V_0 = \frac{1}{4\pi\epsilon_0} \frac{e}{a_0} = 27.17 \text{ V}$$

$$U_0 = -eV_0 = -27.17 \text{ eV} = -4.35 \cdot 10^{-19} \text{ J}$$

$$* \bar{E}_K = \frac{1}{2} m v^2$$

$$\sim \frac{m v^2}{r}$$

$$m \frac{v^2}{a_0} = \frac{1}{4\pi\epsilon_0} \frac{e^2}{a_0^2}$$

$$\bar{E}_K = \frac{1}{2} m v^2 = \frac{1}{8\pi\epsilon_0} \frac{e^2}{a_0} = 2.176 \cdot 10^{-18} \text{ J} = 13.58 \text{ eV}$$

$$\bar{E}_{\text{tot}} = \bar{E}_K + U_0 = \frac{1}{8\pi\epsilon_0} \frac{e^2}{a_0} - \frac{1}{4\pi\epsilon_0} \frac{e^2}{a_0} = -\frac{1}{8\pi\epsilon_0} \frac{e^2}{a_0} = -2.176 \cdot 10^{-18} \text{ J} = -13.6 \text{ eV}$$

(3-7) $\rho = 1.6 \mu\text{C}/\text{m}^3$, $R = 10 \text{ mm}$ sfera

$\frac{U}{V}$

$$u(\vec{r}) = \frac{\epsilon_0}{2} \vec{E}_0^2(\vec{r}) = \frac{\epsilon_0}{2} \vec{E}_0(\vec{r}) \cdot \vec{E}_0(\vec{r})$$

$$U = \int_{\tau_0}^{\tau_{\infty}} u d\tau = \int_{\tau_0}^{\tau_{\infty}} \frac{\epsilon_0}{2} \vec{E}_0^2 d\tau = \frac{\epsilon_0}{2} \int_{S=\partial\tau} V_0(\vec{r}) \vec{G}_0(\vec{r}) \cdot d\vec{S} + \frac{\epsilon_0}{2} \int_{\tau} \vec{G}_0^2(\vec{r}) d\tau$$

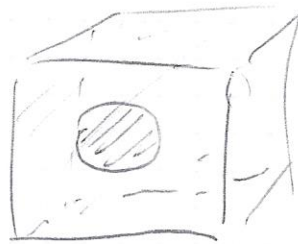
$$\vec{E}_0(r) = \begin{cases} \frac{\rho}{3\epsilon_0} r \hat{e}_r & r \leq R \\ \frac{\rho R^3}{3\epsilon_0 r^2} \hat{e}_r & r > R \end{cases}$$

$$U = \int_{\tau_{\infty}} 4\pi r^2 \frac{\epsilon_0}{2} \left[\int_0^R \left(\frac{\rho r}{3\epsilon_0}\right)^2 4\pi r^2 dr + \int_R^{+\infty} \left(\frac{\rho R^3}{3\epsilon_0 r^2}\right)^2 4\pi r^2 dr \right]$$

$$= \frac{\epsilon_0}{2} \left[\frac{4\pi\rho^2}{9\epsilon_0^2} \frac{1}{5} (R^5 - \phi) + \frac{4\pi\rho^2 R^6}{9\epsilon_0} \left(-\phi + \frac{1}{R}\right) \right]$$

$$= \frac{4\pi\rho^2 R^5}{15\epsilon_0} = 1.51 \cdot 10^{-5} \text{ J}$$

$$U = \frac{\epsilon_0}{2} \int_{S=\partial\tau} (V_0 \vec{E}_0) \cdot d\vec{S} + \frac{\epsilon_0}{2} \int_{\tau} \vec{E}_0^2 d\tau \quad V_0(r) = \frac{\rho R^3}{3\epsilon_0 r}$$



$$= \frac{\epsilon_0}{2} \underbrace{\frac{\rho R^3}{3\epsilon_0 r}}_{V_0(r)} \cdot \underbrace{\frac{\rho R^3}{3\epsilon_0 r^2}}_{\vec{E}_0(r)} \cdot \underbrace{4\pi r^2}_{dS(r)} + \frac{\epsilon_0}{2} \left[\int_0^R + \int_R^{+\infty} \vec{E}_0^2(r) 4\pi r^2 dr \right]$$

$$= \cancel{\frac{\epsilon_0}{2} \frac{\rho R^6}{9\epsilon_0} \frac{4\pi}{r}} + \frac{\epsilon_0}{2} \left[\frac{1}{5} \frac{4\pi\rho^2 R^5}{9\epsilon_0} + \frac{4\pi\rho^2 R^6}{9\epsilon_0} \left(\frac{1}{R} - \frac{1}{r} \right) \right]$$

$$= \frac{4\pi\rho^2 R^5}{15\epsilon_0} = 1.51 \cdot 10^{-5} \text{ J}$$

Gradiente

f

$$df = \nabla f \cdot d\vec{l}$$

$$\nabla f = \frac{df}{d\vec{l}} \hat{d\vec{l}}$$

(A)

$$d\vec{l} = (dx, dy, dz)$$

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz$$



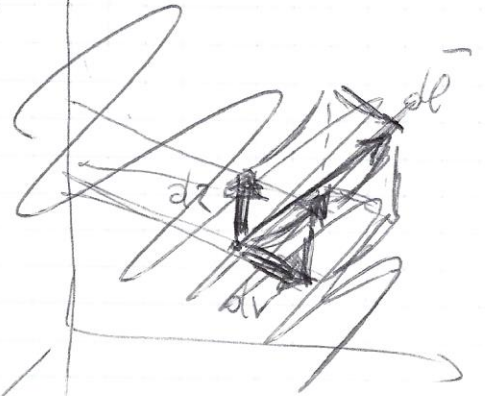
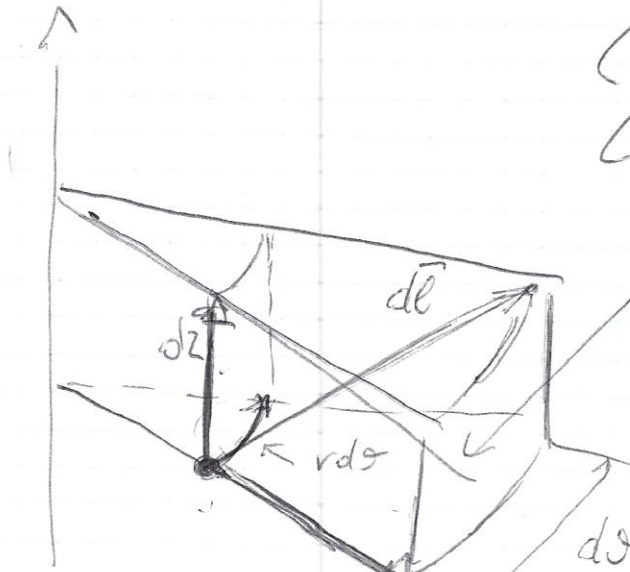
$$\left[\frac{\partial f}{\partial x} \right] dx + \left[\frac{\partial f}{\partial y} \right] dy + \left[\frac{\partial f}{\partial z} \right] dz = (\nabla f)_x dx + (\nabla f)_y dy + (\nabla f)_z dz$$

$$\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) = \frac{\partial f}{\partial x} \hat{e}_x + \frac{\partial f}{\partial y} \hat{e}_y + \frac{\partial f}{\partial z} \hat{e}_z$$

(B)

r, \vartheta, z

$$d\vec{l} = (dr, r d\vartheta, dz)$$

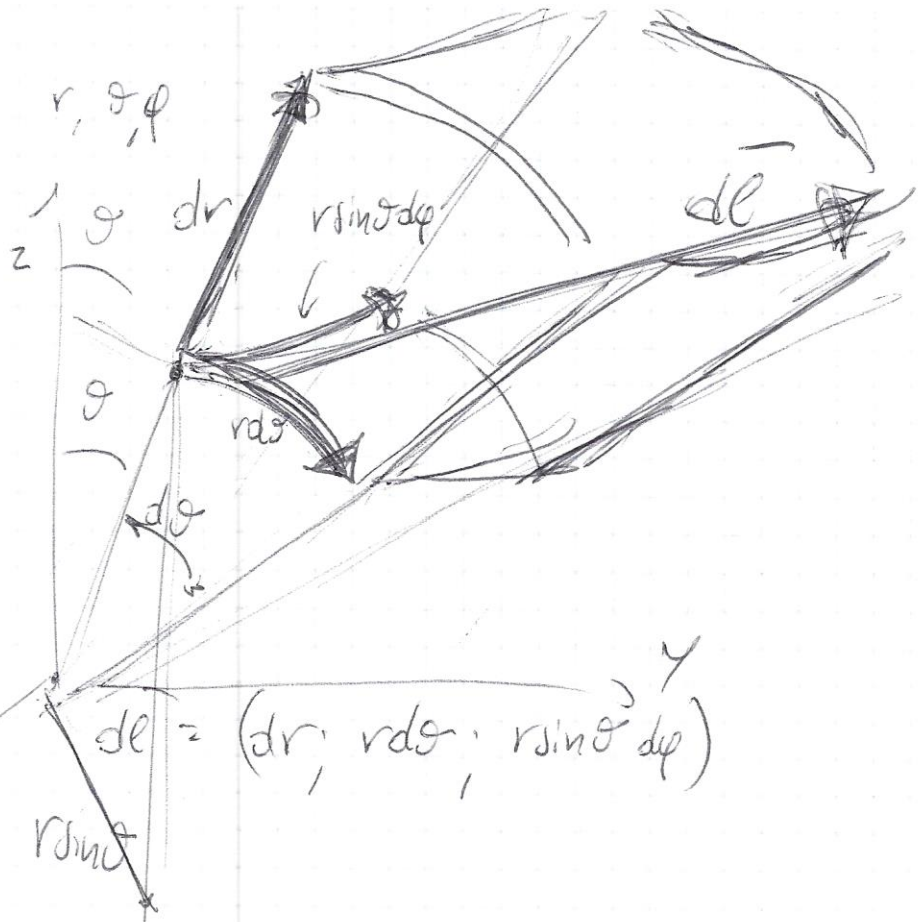


$$df = \left[\frac{\partial f}{\partial r} \right] dr + \left[\frac{\partial f}{\partial \vartheta} \right] r d\vartheta + \left[\frac{\partial f}{\partial z} \right] dz = (\nabla f)_r dr + (\nabla f)_\vartheta r d\vartheta + (\nabla f)_z dz$$

$$\nabla f = \frac{\partial f}{\partial r} \hat{e}_r + \frac{1}{r} \frac{\partial f}{\partial \vartheta} \hat{e}_\vartheta + \frac{\partial f}{\partial z} \hat{e}_z$$

(c)

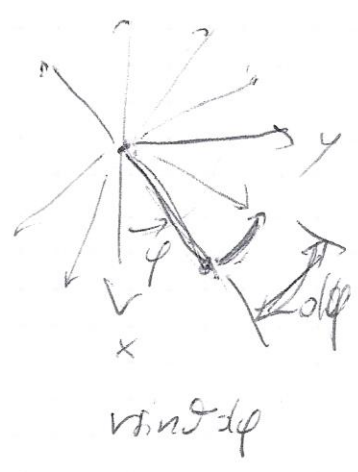
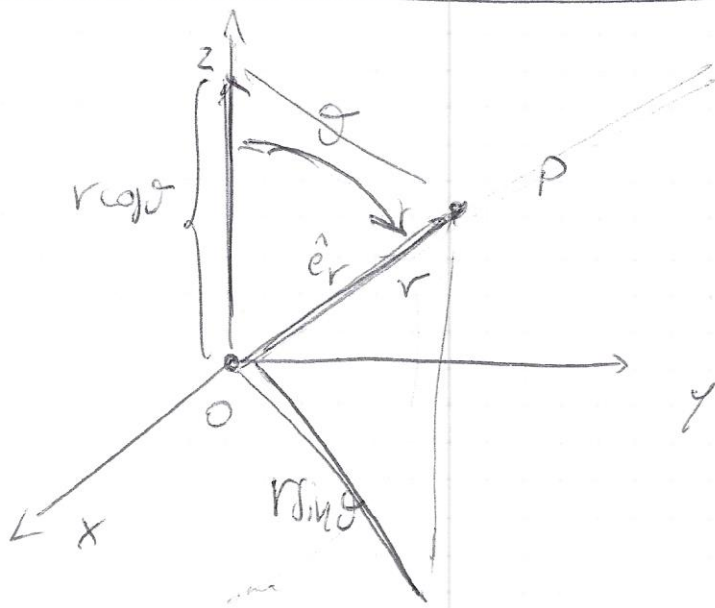
$d\vec{r}$



$$d\vec{r} = (dr, r d\theta, r \sin\theta d\phi)$$

$$\vec{\nabla} f = \frac{\partial f}{\partial r} \hat{e}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{e}_\theta + \frac{1}{r \sin\theta} \frac{\partial f}{\partial \phi} \hat{e}_\phi$$

$$\vec{\nabla} f = \frac{\partial f}{\partial r} \hat{e}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{e}_\theta + \frac{1}{r \sin\theta} \frac{\partial f}{\partial \phi} \hat{e}_\phi$$



Divergenz

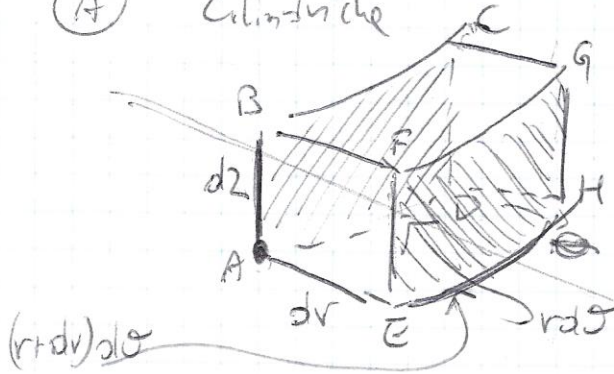
$$\Phi(\vec{v}) = \int_{\Sigma=\partial Z} \vec{v} \cdot d\vec{S} = \int_Z \operatorname{div} \vec{v} \, dz$$

$$\operatorname{div}(\vec{v}) = \nabla \cdot \vec{v}$$

$$d\Phi(\vec{v}) = \operatorname{div}(\vec{v}) \, dz$$

(A)

Cylindrische



(v)

$A(r, \theta, z)$

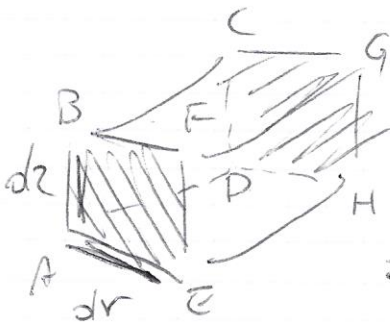
$$d\Phi_{ABCD} = \vec{v}(r, \theta, z) \cdot d\vec{S} = -v_r \, r \, d\theta \, dz$$

$$d\Phi_{EFGH} = \vec{v}(r+dr, \theta, z) \cdot d\vec{S} = \left[v_r(r, \theta, z) + \frac{\partial v_r}{\partial r} dr \right] (r+dr) d\theta \, dz = v_r r d\theta \, dz + (v_r) dr d\theta \, dz + \frac{\partial v_r}{\partial r} r dr d\theta \, dz + \frac{\partial v_r}{\partial r} (dr)^2 d\theta \, dz$$

$$\frac{\partial}{\partial r} (r v_r) = v_r + r \frac{\partial v_r}{\partial r}$$

$$d\Phi_r = \frac{\partial}{\partial r} (r v_r) dr d\theta \, dz = \frac{1}{r} \frac{\partial}{\partial r} (r v_r) r dr d\theta \, dz = \frac{\partial}{\partial r} (r v_r) dr d\theta \, dz$$

(B)



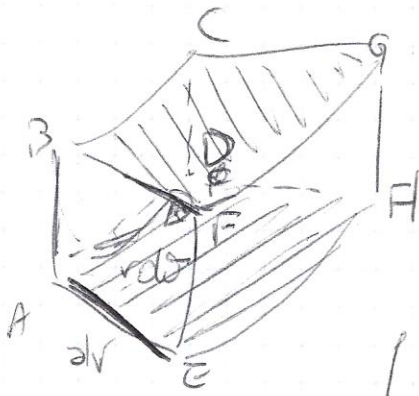
$$d\Phi_{ABFG} = \vec{v}(r, \theta, z) \cdot d\vec{S} = -v_\theta \, dr \, dz$$

$$d\Phi_{EDHG} = \vec{v}(r, \theta+dr, z) \cdot d\vec{S} =$$

$$= \left[v_\theta(r, \theta, z) + \frac{\partial v_\theta}{\partial \theta} d\theta \right] dr \, dz = v_\theta \, dr \, dz + \frac{\partial v_\theta}{\partial \theta} dr \, dz$$

$$d\Phi_{\theta} = \frac{\partial v_\theta}{\partial \theta} dr \, dz = \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} dz$$

(2)



$$d\Phi_{ADHG} = -v_z(r, \theta, z) r dr d\theta$$

$$d\Phi_{EFGH} = v_z(r, \theta, z) r dr d\theta$$

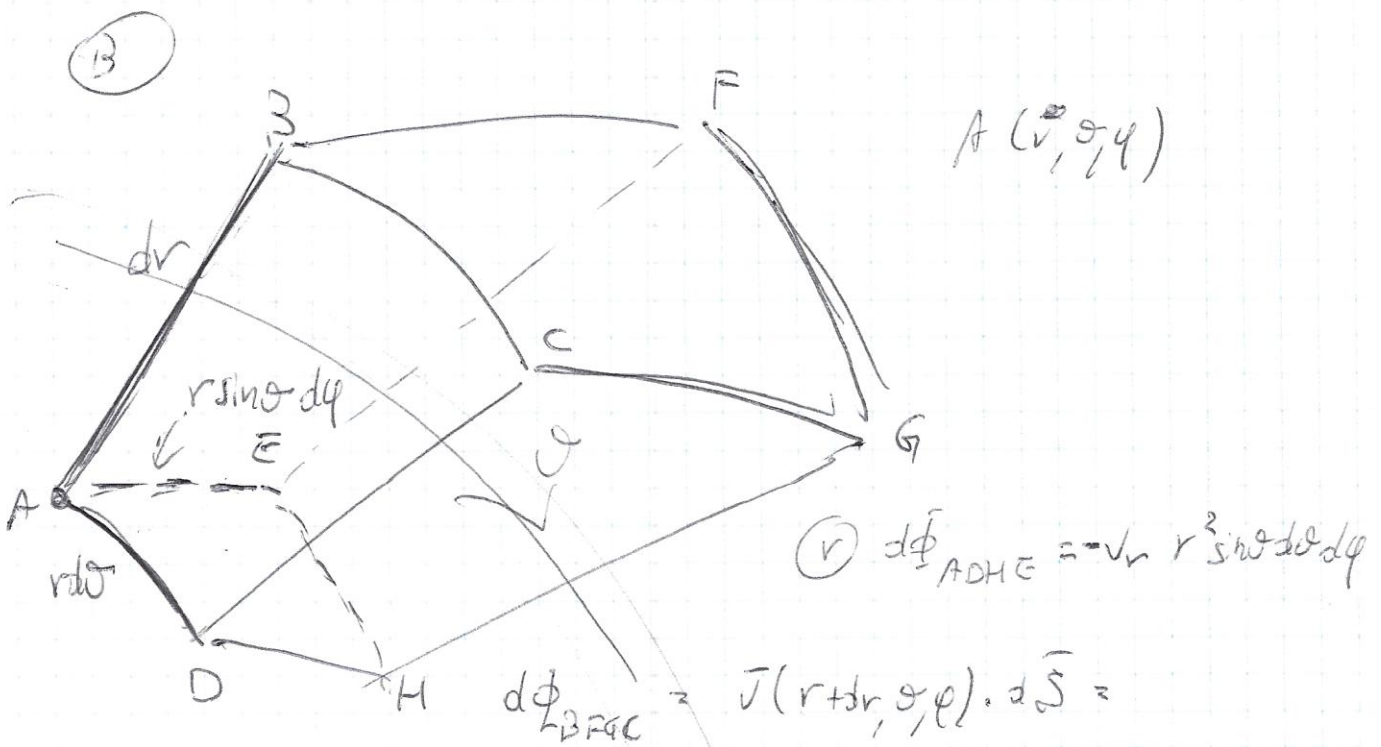
$$= \left[v_z(r, \theta, z) + \frac{\partial v_z}{\partial z} dz \right] r dr d\theta$$

$$d\Phi_z = \frac{\partial v_z}{\partial z} r dr d\theta dz = \frac{\partial v_z}{\partial z} dz$$

$$d\Phi_{tot} = d\Phi_r + d\Phi_\theta + d\Phi_z =$$

$$= \left[\frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z} \right] dz$$

$\text{div}(\vec{v})$



$A(r, \theta, \phi)$

(v) $d\Phi_{ADHE} = -v_r r^2 \sin\theta d\theta d\phi$

$d\Phi_{BFGC} = \vec{J}(r+dr, \theta, \phi) \cdot d\vec{S} =$

$= \left[v_r(r, \theta, \phi) + \frac{\partial v_r}{\partial r} dr \right] (r+dr)^2 \sin\theta d\theta d\phi =$

$= v_r r^2 \sin\theta d\theta d\phi + 2v_r r \sin\theta dr d\theta d\phi + v_r \sin\theta (dr)^2 d\theta d\phi +$

$\frac{\partial v_r}{\partial r} r^2 \sin\theta d\theta d\phi + \frac{\partial v_r}{\partial r} 2r \sin\theta (dr)^2 d\theta d\phi + \frac{\partial v_r}{\partial r} \sin\theta (dr)^3 d\theta d\phi$

$\rightarrow \frac{\partial}{\partial r} (r^2 v_r)$

$\Rightarrow d\Phi_r = \frac{\partial}{\partial r} (r^2 v_r) \sin\theta dr d\theta d\phi$

$d\tau = r^2 \sin\theta dr d\theta d\phi$

$d\Phi_r = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) d\tau$

(g) $d\Phi_{ABFE} = \vec{J}(r, \theta, \phi) \cdot d\vec{S} = -v_\theta r \sin\theta dr d\phi$

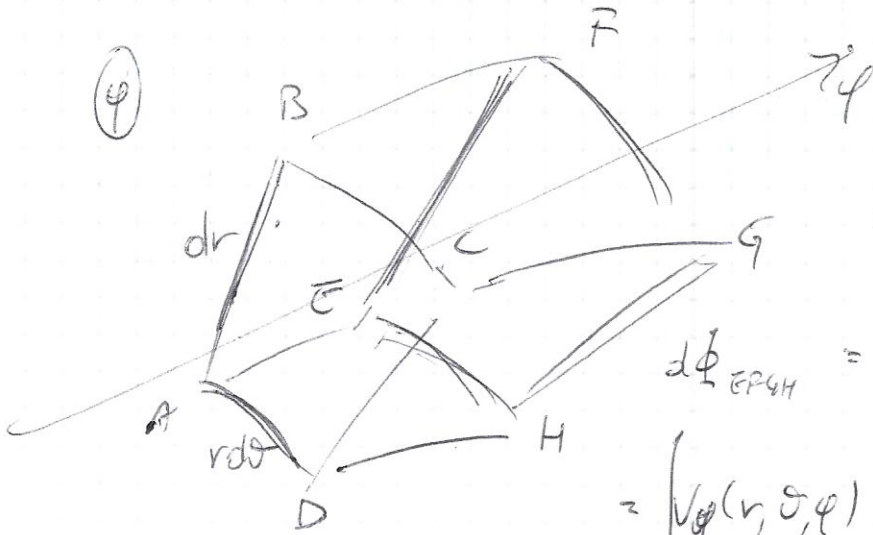
$d\Phi_{DCGH} = \vec{J}(r, \theta+d\theta, \phi) \cdot d\vec{S} = \left[v_\theta(r, \theta, \phi) + \frac{\partial v_\theta}{\partial \theta} d\theta \right] r \sin(\theta+d\theta) dr d\phi =$

$\left[\sin(\theta+d\theta) = \sin\theta + \frac{\partial}{\partial \theta} (\sin\theta) d\theta = \sin\theta + \cos\theta d\theta \right]$

$= v_\theta r \sin\theta dr d\phi + v_\theta r \cos\theta dr d\theta d\phi + \frac{\partial v_\theta}{\partial \theta} r \sin\theta dr d\theta d\phi + \frac{\partial v_\theta}{\partial \theta} r \cos\theta (d\theta)^2 d\phi$

$$\frac{\partial}{\partial \sigma} (\sin \sigma v_\sigma) = v_\sigma \cos \sigma + \sin \sigma \frac{\partial v_\sigma}{\partial \sigma}$$

$$d\bar{\Phi}_\sigma = \frac{\partial}{\partial \sigma} (\sin \sigma v_\sigma) r dr d\sigma d\varphi = \frac{1}{r \sin \sigma} \frac{\partial}{\partial \sigma} (\sin \sigma v_\sigma) dz$$



$$d\bar{\Phi}_{ABCD} = -v_\varphi r dr d\sigma$$

$$d\bar{\Phi}_{EFGH} = \vec{J}(r, \sigma, \varphi + d\varphi) \cdot d\vec{S} =$$

$$= \left[v_\varphi(r, \sigma, \varphi) + \frac{\partial v_\varphi}{\partial \varphi} d\varphi \right] r dr d\sigma$$

$$d\bar{\Phi}_\varphi = \frac{\partial v_\varphi}{\partial \varphi} r dr d\sigma d\varphi = \frac{1}{r \sin \sigma} \frac{\partial v_\varphi}{\partial \varphi} dz$$

$$d\bar{\Phi}_{Tot} = \left[\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \sigma} \frac{\partial}{\partial \sigma} (v_\sigma \sin \sigma) + \frac{1}{r \sin \sigma} \frac{\partial v_\varphi}{\partial \varphi} \right] dz$$

$\underbrace{\hspace{15em}}_{\text{div}(\vec{v})}$

Coord. curvilinee ortogonali

(q_1, q_2, q_3)

$(\hat{e}_1, \hat{e}_2, \hat{e}_3)$

Gradiente $df = \vec{\nabla} f \cdot d\vec{l}$

Coord. q_1 $\hat{e}_i = \frac{1}{h_i} \frac{\partial \vec{r}}{\partial q_i}$ $h_i = \left| \frac{\partial \vec{r}}{\partial q_i} \right|$

spat. element lung $dl_i = h_i(q_1, q_2, q_3) dq_i$

$$d\vec{l} = (dl_1, dl_2, dl_3) = dl_1 \hat{e}_1 + dl_2 \hat{e}_2 + dl_3 \hat{e}_3 = h_1 dq_1 \hat{e}_1 + h_2 dq_2 \hat{e}_2 + h_3 dq_3 \hat{e}_3$$

Cart.: $h_1 = h_2 = h_3 = 1$

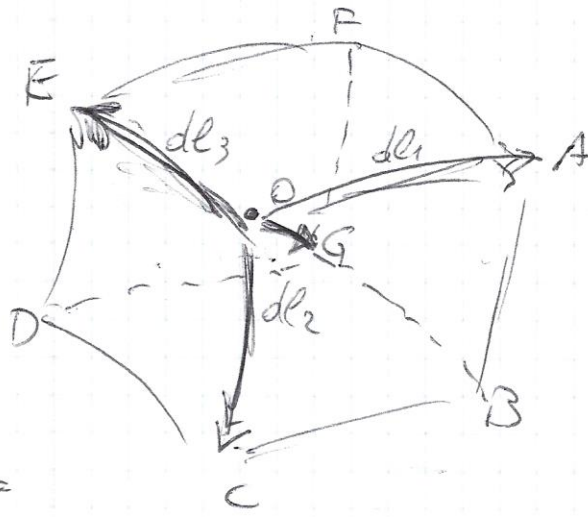
Cyl.: $h_1 = 1$, $h_2 = r$, $h_3 = 1$
 dr , $r d\varphi$, dz

Sph.: $h_1 = 1$, $h_2 = r$, $h_3 = r \sin \theta$

$$df = \frac{\partial f}{\partial q_1} dq_1 + \frac{\partial f}{\partial q_2} dq_2 + \frac{\partial f}{\partial q_3} dq_3 = (\vec{\nabla} f)_1 h_1 dq_1 + (\vec{\nabla} f)_2 h_2 dq_2 + (\vec{\nabla} f)_3 h_3 dq_3$$

$$\vec{\nabla} f = \frac{1}{h_1} \frac{\partial f}{\partial q_1} \hat{e}_1 + \frac{1}{h_2} \frac{\partial f}{\partial q_2} \hat{e}_2 + \frac{1}{h_3} \frac{\partial f}{\partial q_3} \hat{e}_3$$

Divergenz



$$d\vec{\Phi}_1$$

$$d\vec{\Phi}_{OCDE} = \vec{v}(O) \cdot d\vec{S} =$$

$$= -v_1(O) dl_2(O) dl_3(O) = -v_1(O) h_1(O) h_2(O) dq_2 dq_3$$

$$d\vec{\Phi}_{ABCF} = \vec{v}(A) \cdot d\vec{S} = v_1(A) h_2(A) h_3(A) dq_2 dq_3 =$$

$$= \left[(v_1 h_2 h_3)_0 + \frac{\partial}{\partial q_1} (v_1 h_2 h_3)_0 dq_1 \right] dq_2 dq_3$$

$$d\vec{\Phi}_1 = \frac{\partial}{\partial q_1} (v_1 h_2 h_3) dq_1 dq_2 dq_3 = \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial q_1} (v_1 h_2 h_3) d\tau$$

$$d\tau = dl_1 dl_2 dl_3 = h_1 h_2 h_3 dq_1 dq_2 dq_3$$

$$d\vec{\Phi}_2 = \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial q_2} (v_2 h_1 h_3) d\tau$$

$$d\vec{\Phi}_3 = \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial q_3} (v_3 h_1 h_2) d\tau$$

$$d\vec{\Phi}_{\text{net}} = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial q_1} (v_1 h_2 h_3) + \frac{\partial}{\partial q_2} (v_2 h_1 h_3) + \frac{\partial}{\partial q_3} (v_3 h_1 h_2) \right] d\tau$$

-div(v)

$$\vec{\nabla} \cdot \vec{E} = -\rho/\epsilon_0$$

$$\vec{E}_0 = -\vec{\nabla} V_0$$

$$-\vec{\nabla} \cdot (\vec{\nabla} V_0) = -\rho/\epsilon_0$$

$$\boxed{\begin{aligned} \vec{\nabla}^2 V_0 &= -\rho/\epsilon_0 \\ \Delta V_0 &= -\rho/\epsilon_0 \end{aligned}}$$

$$\boxed{\nabla^2 V_0 = \Delta V_0 = -\rho/\epsilon_0}$$

eq. di Poisson

$$\nabla^2 V_0 = \phi \quad \text{eq. di Laplace}$$

$$\vec{u} = \vec{\nabla} f = \frac{\partial f}{\partial x} \hat{e}_x + \frac{\partial f}{\partial y} \hat{e}_y + \frac{\partial f}{\partial z} \hat{e}_z = u_x \hat{e}_x + u_y \hat{e}_y + u_z \hat{e}_z$$

$$\begin{aligned} \vec{\nabla} \cdot \vec{u} &= \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial z} \right) \\ &= \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} \end{aligned}$$

$$\vec{u} = \vec{\nabla} f = \underbrace{\frac{\partial f}{\partial r}}_{u_r} \hat{e}_r + \underbrace{\frac{1}{r} \frac{\partial f}{\partial \theta}}_{u_\theta} \hat{e}_\theta + \underbrace{\frac{\partial f}{\partial z}}_{u_z} \hat{e}_z$$

~~$$\vec{\nabla} \cdot \vec{u} = \frac{1}{r} \frac{\partial}{\partial r} (r u_r) + \frac{1}{r \sin \theta} \left(\frac{\partial}{\partial \theta} (\sin \theta u_\theta) + \frac{\partial}{\partial \phi} (u_\phi) \right) + \frac{\partial u_z}{\partial z}$$~~

$$= \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r \sin \theta} \left(\frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{\partial}{\partial \phi} \left(\frac{\partial f}{\partial \phi} \right) \right) + \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial z} \right)$$

$$= \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial^2 f}{\partial z^2} = \nabla^2 f$$

$$\nabla^2 \vec{E} = \nabla^2 (\epsilon_x \hat{e}_x + \epsilon_y \hat{e}_y + \epsilon_z \hat{e}_z)$$